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Quality Report

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Figure 8: Top view of the image computed positions with a line between matching images. The darkness of the lines indicates the number of matched SIFT responses between the images. Bright lines indicate weak links and require review for points on merge images.

Geolocation Details

Absolute Geolocation Variance

8 out of 11 generated and calibrated images have been labeled as inaccurate.

Min Error [m]	Max Error [m]	Geolocation Error X [m]	Geolocation Error Y [m]	Geolocation Error Z [m]
-	-15.83	0.00	0.00	0.00
-15.83	-12.00	0.00	0.00	0.00
-12.00	-8.00	0.00	0.00	0.00
-8.00	-4.00	0.00	0.00	0.00
-4.00	0.00	0.00	7.69	0.00
-3.00	0.00	48.15	46.15	53.85
0.00	3.00	59.85	38.66	48.15
3.00	8.00	0.00	7.69	0.00
6.00	8.00	0.00	0.00	0.00
9.00	12.00	0.00	0.00	0.00
12.00	15.00	0.00	0.00	0.00
15.00	-	0.00	0.00	0.00
Mean [m]		0.000008	-0.000004	-0.000077
Sigma [m]		2.201847	0.288150	0.288150
RMS Error [m]		2.201847	0.288151	0.288151

Min Error and Max Error represent geolocation error intervals between -1.0 and 1.0 times the maximum magnitude of all the images. Columns X, Y, Z show the percentage of images with geolocation error within the provided error tolerance. The geolocation error is the difference between the real and computed image positions. Note that the image geolocation errors do not correspond to the accuracy of the absolute 3D points.

Relative Geolocation Variance

Relative Geolocation Error	Images X [%]	Images Y [%]	Images Z [%]
[1.00, 1.00]	100.00	100.00	100.00
[2.00, 2.00]	100.00	100.00	100.00
[3.00, 3.00]	100.00	100.00	100.00
Mean of Geolocation Accuracy [m]	5.000000	5.000000	10.000000
Sigma of Geolocation Accuracy [m]	0.000000	0.000000	0.000000

Images X, Y, Z represent the percentage of images with a relative geolocation error in X, Y, Z.

Processing Options

Hardware	CPU Intel(R) Xeon(R) CPU E5-1680 v4 @ 3.70GHz
	RAM 16GB
	CPU 16 vCPU (Dedicated)
Operating System	Debian 11.5.0 amd64
Camera Model Name	CanonEOS2204HS_A3_4300x3000 (R08)
Image Coordinate System	WGS84
Output Coordinate System	WGS84 / UTM zone 32N (epsg:31466)
Keypoints Image Scale	Full Image Scale: 1
Advanced Matching Image Pair	Aerial Only or Corridor
Advanced Matching Strategy	Use Externally Verified Matching: no
Advanced Keypoint Extraction	Targeted Number of Keypoints: Automatic
Advanced Calibration	Calibration Method: Standard, Internal Parameters Optimization: no, External Parameters Optimization: no, Retest: yes

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